

3.2 BINARY SEARCH TREES



- ▶ BSTs
- ▶ ordered operations
- ▶ deletion

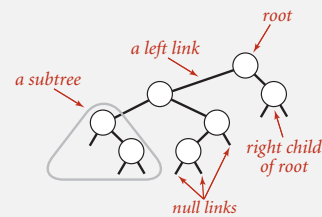
- ▶ BSTs
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Binary search trees

Definition. A BST is a binary tree in symmetric order.

A binary tree is either:

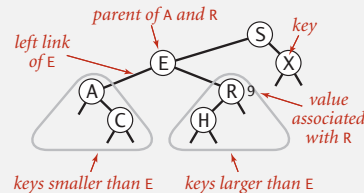
- Empty.
- Two disjoint binary trees (left and right).



Anatomy of a binary tree

Symmetric order. Each node has a key, and every node's key is:

- Larger than all keys in its left subtree.
- Smaller than all keys in its right subtree.



Anatomy of a binary search tree

BST representation in Java

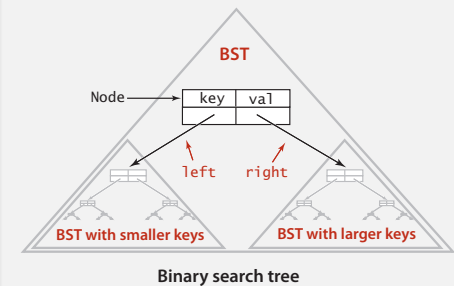
Java definition. A BST is a reference to a root `Node`.

A `Node` is comprised of four fields:

- A `Key` and a `Value`.
- A reference to the left and right subtree.

↑ smaller keys ↑ larger keys

```
private class Node
{
    private Key key;
    private Value val;
    private Node left, right;
    public Node(Key key, Value val)
    {
        this.key = key;
        this.val = val;
    }
}
```



Key and Value are generic types; Key is Comparable

BST implementation (skeleton)

```
public class BST<Key extends Comparable<Key>, Value>
{
    private Node root; ← root of BST

    private class Node
    { /* see previous slide */ }

    public void put(Key key, Value val)
    { /* see next slides */ }

    public Value get(Key key)
    { /* see next slides */ }

    public void delete(Key key)
    { /* see next slides */ }

    public Iterable<Key> iterator()
    { /* see next slides */ }
}
```

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BST search and insert demo

BST search: Java implementation

Get. Return value corresponding to given key, or null if no such key.

```
public Value get(Key key)
{
    Node x = root;
    while (x != null)
    {
        int cmp = key.compareTo(x.key);
        if (cmp < 0) x = x.left;
        else if (cmp > 0) x = x.right;
        else if (cmp == 0) return x.val;
    }
    return null;
}
```

Cost. Number of compares is equal to 1 + depth of node.

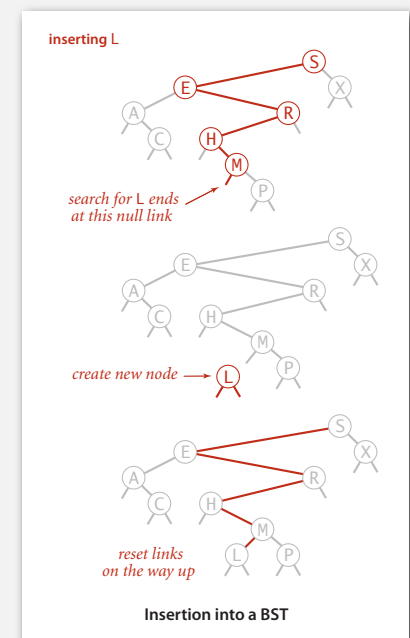
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BST insert

Put. Associate value with key.

Search for key, then two cases:

- Key in tree ⇒ reset value.
- Key not in tree ⇒ add new node.



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BST insert: Java implementation

Put. Associate value with key.

```
public void put(Key key, Value val)
{ root = put(root, key, val); }

private Node put(Node x, Key key, Value val)
{
    if (x == null) return new Node(key, val);
    int cmp = key.compareTo(x.key);
    if (cmp < 0)
        x.left = put(x.left, key, val);
    else if (cmp > 0)
        x.right = put(x.right, key, val);
    else if (cmp == 0)
        x.val = val;
    return x;
}
```

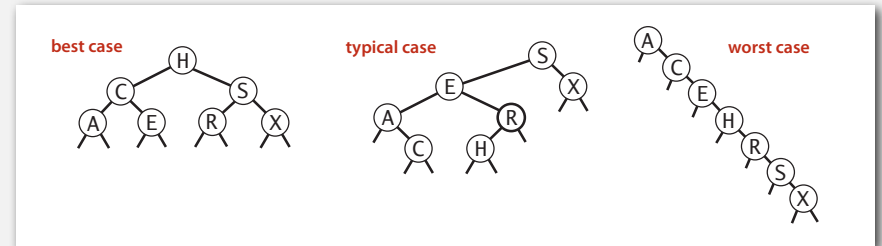
concise, but tricky,
recursive code;
read carefully!

Cost. Number of compares is equal to 1 + depth of node.

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Tree shape

- Many BSTs correspond to same set of keys.
- Number of compares for search/insert is equal to 1 + depth of node.

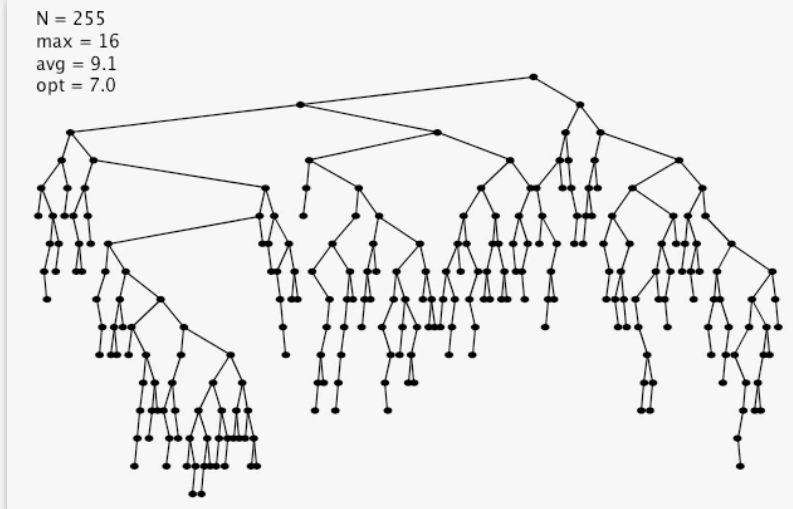


Remark. Tree shape depends on order of insertion.

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BST insertion: random order visualization

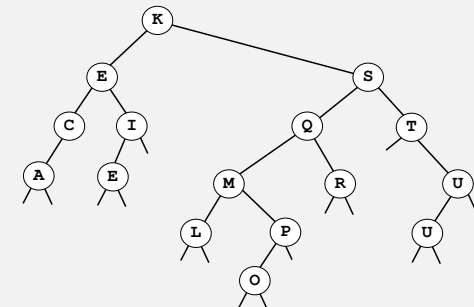
Ex. Insert keys in random order.



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Correspondence between BSTs and quicksort partitioning

Q	U	I	C	K	S	O	R	T	E	X	A	M	P	L	E
E	R	A	T	E	S	L	P	U	I	M	Q	C	X	O	K
E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
A	C	E	I	E	K	L	P	U	T	M	Q	R	X	O	S
A	C	E	I	E	K	L	P	U	T	M	Q	R	X	O	S
A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
A	C	E	E	I	K	L	P	O	R	M	Q	S	X	U	T
A	C	E	E	I	K	L	P	O	M	Q	R	S	X	U	T
A	C	E	E	I	K	L	M	O	P	Q	R	S	X	U	T
A	C	E	E	I	K	L	M	O	P	Q	R	S	X	U	T
A	C	E	E	I	K	L	M	O	P	Q	R	S	X	U	T
A	C	E	E	I	K	L	M	O	P	Q	R	S	X	U	T
A	C	E	E	I	K	L	M	O	P	Q	R	S	X	U	T
A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X



Remark. Correspondence is 1-1 if array has no duplicate keys.

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Proposition. If N distinct keys are inserted into a BST in **random order**, the expected number of compares for a search/insert is $\sim 2 \ln N$.

Pf. 1-1 correspondence with quicksort partitioning.

Proposition. [Reed, 2003] If N distinct keys are inserted in random order, expected height of tree is $\sim 4.311 \ln N$.

How Tall is a Tree?

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ABSTRACT
Let H_n be the height of a random binary search tree on n nodes. We show that there exists constants $\alpha = 4.31107\dots$ and $\beta = 1.95\dots$ such that $E(H_n) = \alpha \log n - \beta \log \log n + O(1)$. We also show that $\text{Var}(H_n) = O(1)$.

But... Worst-case height is N .
(exponentially small chance when keys are inserted in random order)

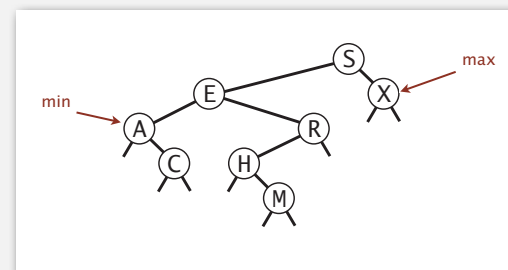
implementation	guarantee		average case		ordered ops?	operations on keys
	search	insert	search hit	insert		
sequential search (unordered list)	N	N	$N/2$	N	no	<code>equals()</code>
binary search (ordered array)	$\lg N$	N	$\lg N$	$N/2$	yes	<code>compareTo()</code>
BST	N	N	$1.39 \lg N$	$1.39 \lg N$?	<code>compareTo()</code>

- ▶ BSTs
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Minimum and maximum

Minimum. Smallest key in table.

Maximum. Largest key in table.

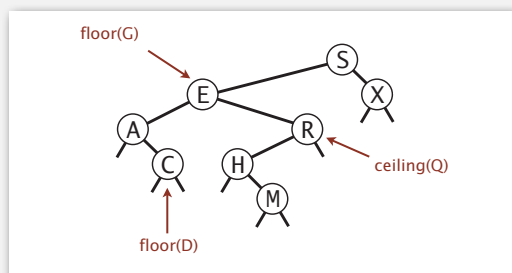


Q. How to find the min / max?

Floor and ceiling

Floor. Largest key \leq to a given key.

Ceiling. Smallest key \geq to a given key.



Q. How to find the floor /ceiling?

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Computing the floor

Case 1. [k equals the key at root]

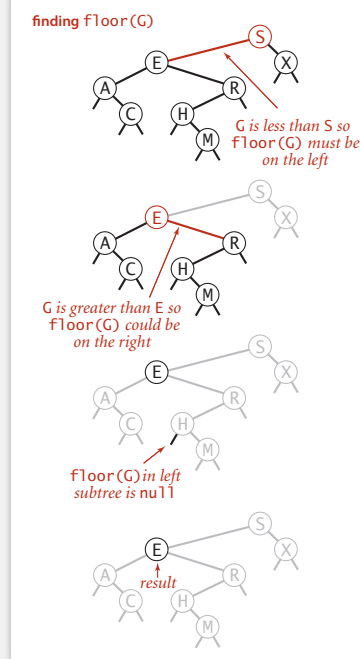
The floor of k is k .

Case 2. [k is less than the key at root]

The floor of k is in the left subtree.

Case 3. [k is greater than the key at root]

The floor of k is in the right subtree
(if there is **any** key $\leq k$ in right subtree);
otherwise it is the key in the root.



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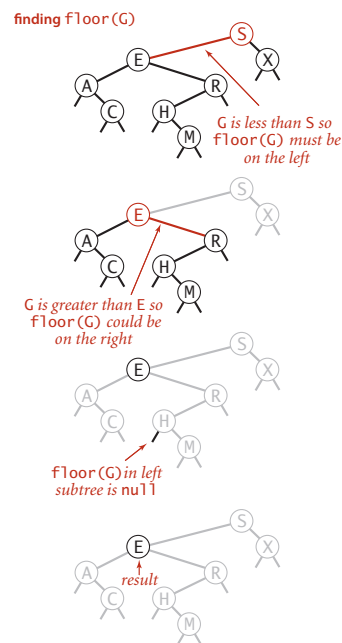
Computing the floor

```
public Key floor(Key key)
{
    Node x = floor(root, key);
    if (x == null) return null;
    return x.key;
}
private Node floor(Node x, Key key)
{
    if (x == null) return null;
    int cmp = key.compareTo(x.key);

    if (cmp == 0) return x;

    if (cmp < 0) return floor(x.left, key);

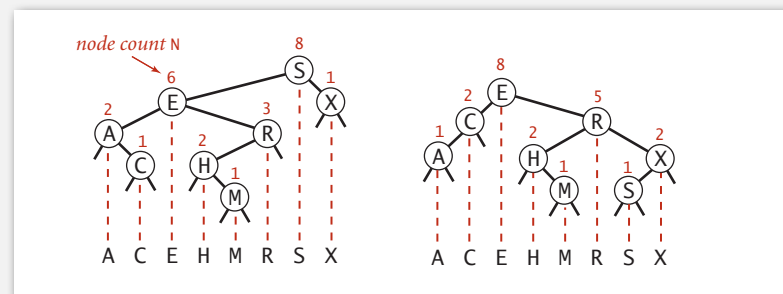
    Node t = floor(x.right, key);
    if (t != null) return t;
    else return x;
}
```



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Subtree counts

In each node, we store the number of nodes in the subtree rooted at that node.
To implement `size()`, return the count at the root.



Remark. This facilitates efficient implementation of `rank()` and `select()`.

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BST implementation: subtree counts

```
private class Node
{
    private Key key;
    private Value val;
    private Node left;
    private Node right;
    private int N;
}
```

number of nodes
in subtree

```
public int size()
{ return size(root); }
```

```
private int size(Node x)
{
    if (x == null) return 0;
    return x.N;
}
```

ok to call when x is null

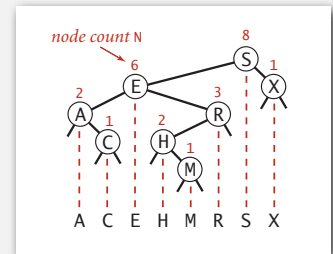
```
private Node put(Node x, Key key, Value val)
{
    if (x == null) return new Node(key, val);
    int cmp = key.compareTo(x.key);
    if (cmp < 0) x.left = put(x.left, key, val);
    else if (cmp > 0) x.right = put(x.right, key, val);
    else if (cmp == 0) x.val = val;
    x.N = 1 + size(x.left) + size(x.right);
    return x;
}
```

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Rank

Rank. How many keys $< k$?

Easy recursive algorithm (4 cases!)



```
public int rank(Key key)
{ return rank(key, root); }

private int rank(Key key, Node x)
{
    if (x == null) return 0;
    int cmp = key.compareTo(x.key);
    if (cmp < 0) return rank(key, x.left);
    else if (cmp > 0) return 1 + size(x.left) + rank(key, x.right);
    else if (cmp == 0) return size(x.left);
}
```

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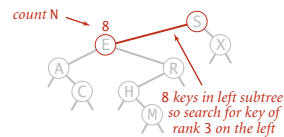
Selection

Select. Key of given rank.

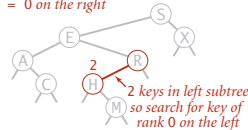
```
public Key select(int k)
{
    if (k < 0) return null;
    if (k >= size()) return null;
    Node x = select(root, k);
    return x.key;
}
```

```
private Node select(Node x, int k)
{
    if (x == null) return null;
    int t = size(x.left);
    if (t > k)
        return select(x.left, k);
    else if (t < k)
        return select(x.right, k-t-1);
    else if (t == k)
        return x;
}
```

finding select(3)
the key of rank 3



2 keys in left subtree so
search for key of rank
3-2-1 = 0 on the right



0 keys in left subtree
and searching for
key of rank 0
so return H

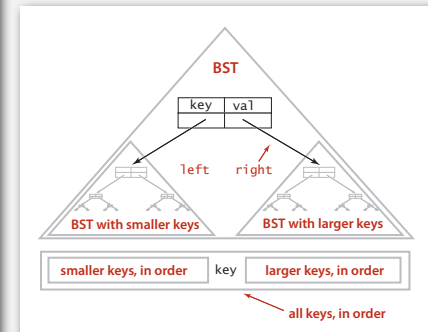
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Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.

```
public Iterable<Key> keys ()
{
    Queue<Key> q = new Queue<Key>();
    inorder(root, q);
    return q;
}

private void inorder(Node x, Queue<Key> q)
{
    if (x == null) return;
    inorder(x.left, q);
    q.enqueue(x.key);
    inorder(x.right, q);
}
```

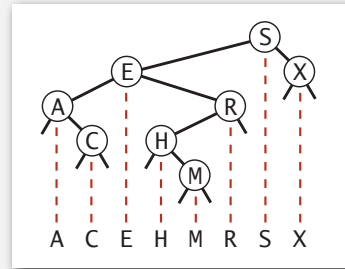
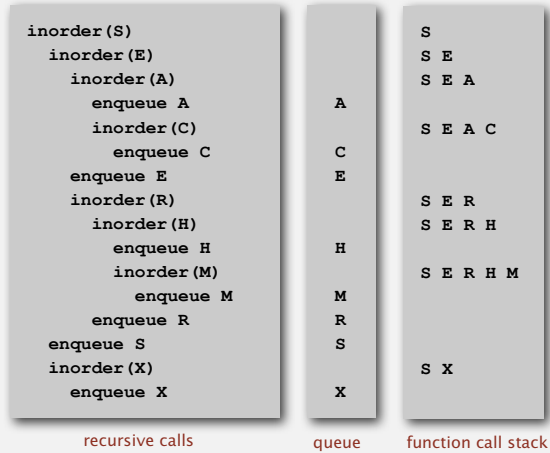


Property. Inorder traversal of a BST yields keys in ascending order.

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Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.



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BST: ordered symbol table operations summary

	sequential search	binary search	BST
search	N	lg N	h
insert	1	N	h
min / max	N	1	h
floor / ceiling	N	lg N	h
rank	N	lg N	h
select	N	1	h
ordered iteration	N log N	N	N

h = height of BST
(proportional to log N
if keys inserted in random order)

order of growth of running time of ordered symbol table operations

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- BSTs
- ordered operations
- deletion

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ST implementations: summary

implementation	guarantee			average case			ordered iteration?	operations on keys
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	N	N	N	N/2	N	N/2	no	<code>equals()</code>
binary search (ordered array)	lg N	N	N	lg N	N/2	N/2	yes	<code>compareTo()</code>
BST	N	N	N	1.39 lg N	1.39 lg N	???	yes	<code>compareTo()</code>

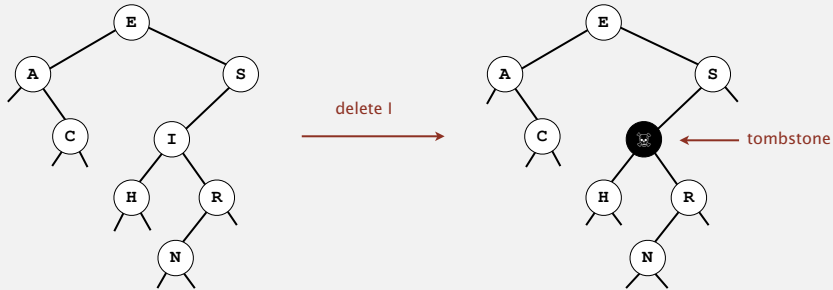
Next. Deletion in BSTs.

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BST deletion: lazy approach

To remove a node with a given key:

- Set its value to `null`.
- Leave key in tree to guide searches (but don't consider it equal to search key).



Cost. $\sim 2 \ln N'$ per insert, search, and delete (if keys in random order), where N' is the number of key-value pairs ever inserted in the BST.

Unsatisfactory solution. Tombstone overload.

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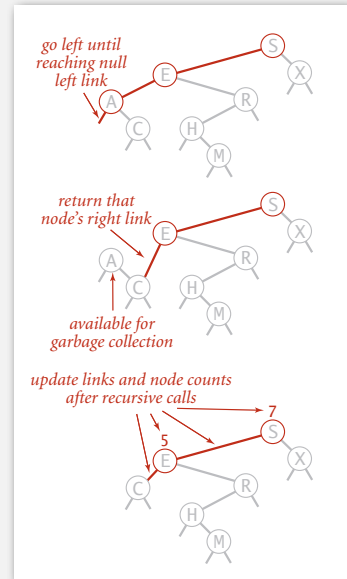
Deleting the minimum

To delete the minimum key:

- Go left until finding a node with a null left link.
- Replace that node by its right link.
- Update subtree counts.

```
public void deleteMin()
{ root = deleteMin(root); }

private Node deleteMin(Node x)
{
    if (x.left == null) return x.right;
    x.left = deleteMin(x.left);
    x.N = 1 + size(x.left) + size(x.right);
    return x;
}
```

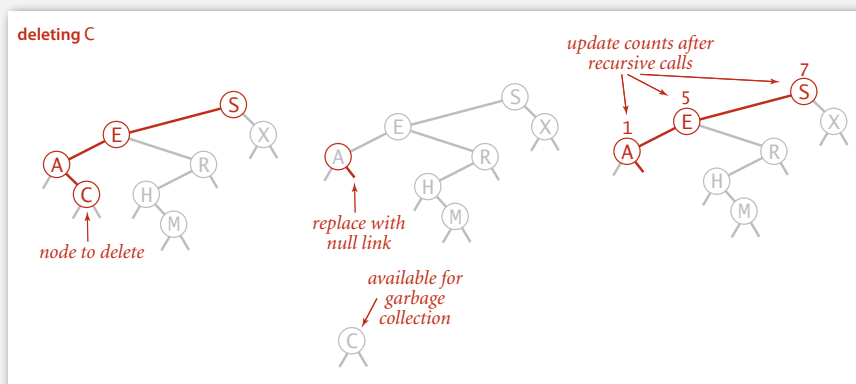


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Hibbard deletion

To delete a node with key k : search for node t containing key k .

Case 0. [0 children] Delete t by setting parent link to null.

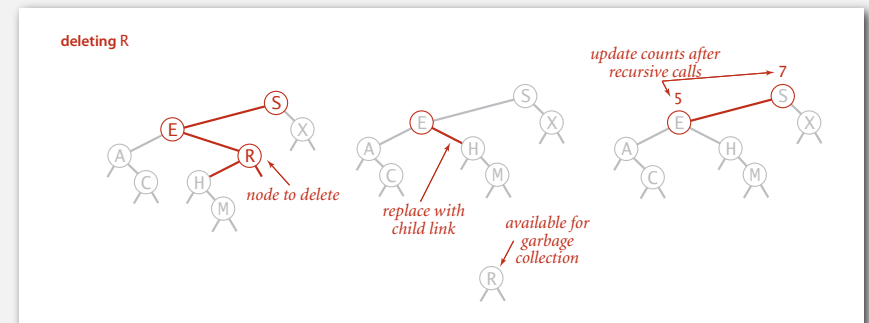


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Hibbard deletion

To delete a node with key k : search for node t containing key k .

Case 1. [1 child] Delete t by replacing parent link.



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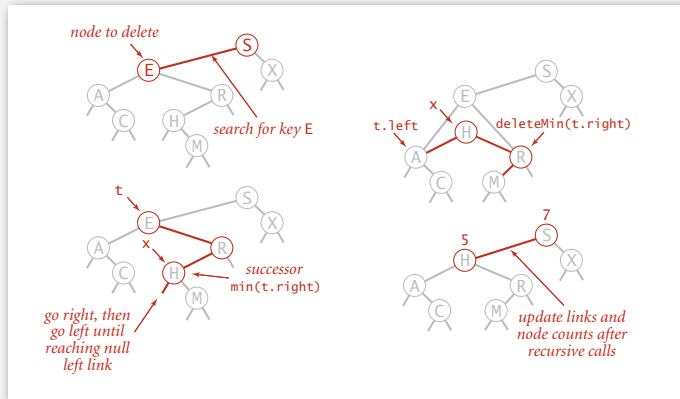
Hibbard deletion

To delete a node with key k : search for node t containing key k .

Case 2. [2 children]

- Find successor x of t .
- Delete the minimum in t 's right subtree.
- Put x in t 's spot.

- ← x has no left child
- ← but don't garbage collect x
- ← still a BST



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Hibbard deletion: Java implementation

```
public void delete(Key key)
{ root = delete(root, key); }

private Node delete(Node x, Key key) {
    if (x == null) return null;
    int cmp = key.compareTo(x.key);
    if (cmp < 0) x.left = delete(x.left, key);
    else if (cmp > 0) x.right = delete(x.right, key);
    else {
        if (x.right == null) return x.left;

        Node t = x;
        x = min(t.right);
        x.right = deleteMin(t.right);
        x.left = t.left;
    }
    x.N = size(x.left) + size(x.right) + 1;
    return x;
}
```

← search for key

← no right child

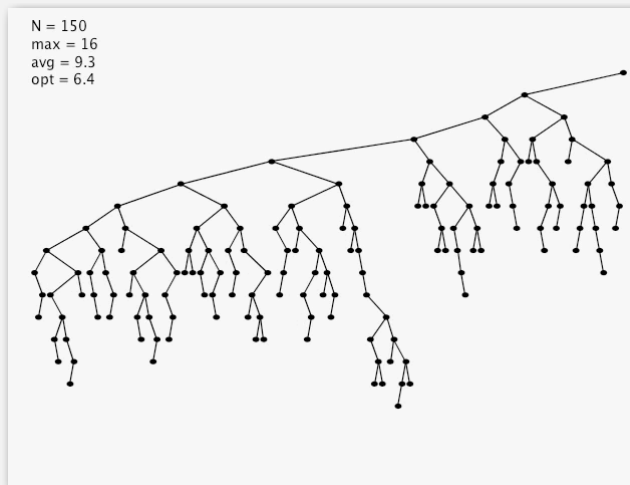
← replace with successor

← update subtree counts

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Hibbard deletion: analysis

Unsatisfactory solution. Not symmetric.



Surprising consequence. Trees not random (!) \Rightarrow $\sqrt{\lg N}$ per op.
Longstanding open problem. Simple and efficient delete for BSTs.

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ST implementations: summary

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binary search (ordered array)	$\lg N$	N	N	$\lg N$	N/2	N/2	yes	<code>compareTo()</code>
BST	N	N	N	$1.39 \lg N$	$1.39 \lg N$	\sqrt{N}	yes	<code>compareTo()</code>

← other operations also become \sqrt{N} if deletions allowed

Red-black BST. Guarantee logarithmic performance for all operations.

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